

INTEGER OPTIMIZATION AND COMPUTATIONAL TOPOLOGY

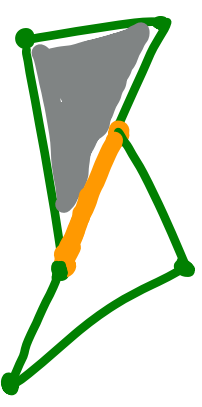
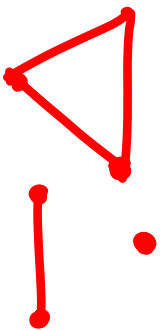
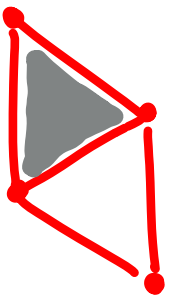
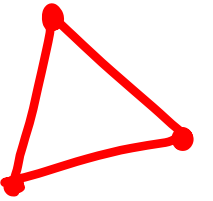
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SIMPLICIAL COMPLEX

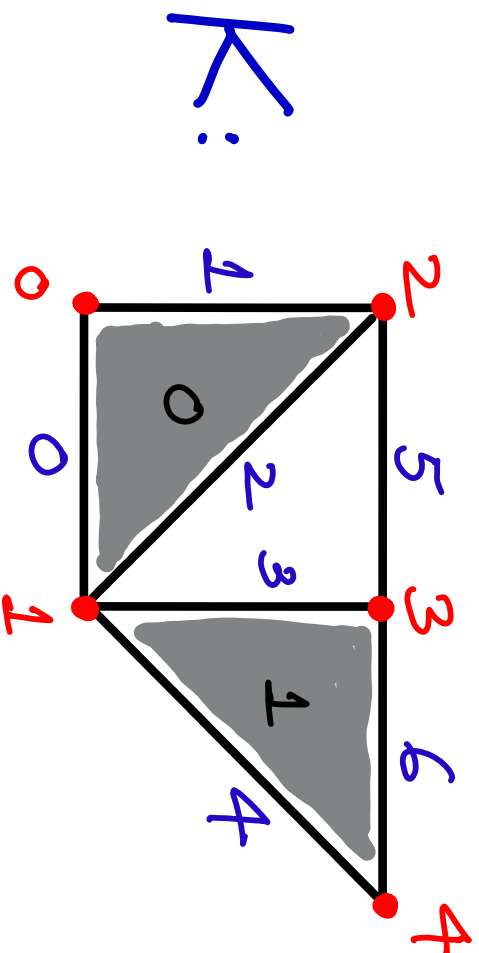
K : a collection of simplices in \mathbb{R}^d such that

- (1) every face of a simplex in K is in K ;
- (2) intersection of two simplices of K is a face of each of them.



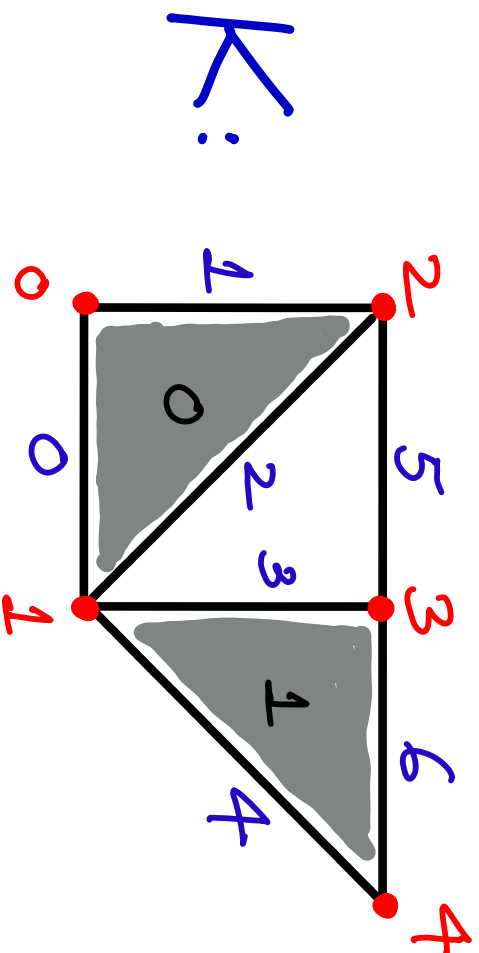
not a simplicial complex \leftarrow

AN EXAMPLE

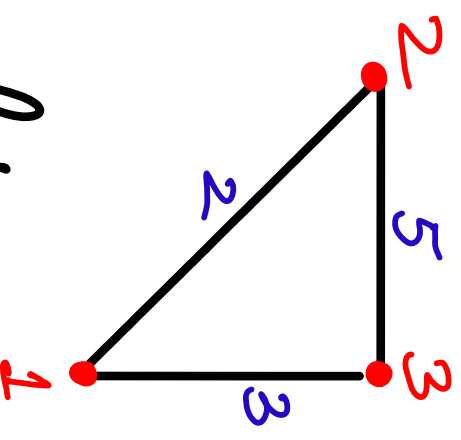
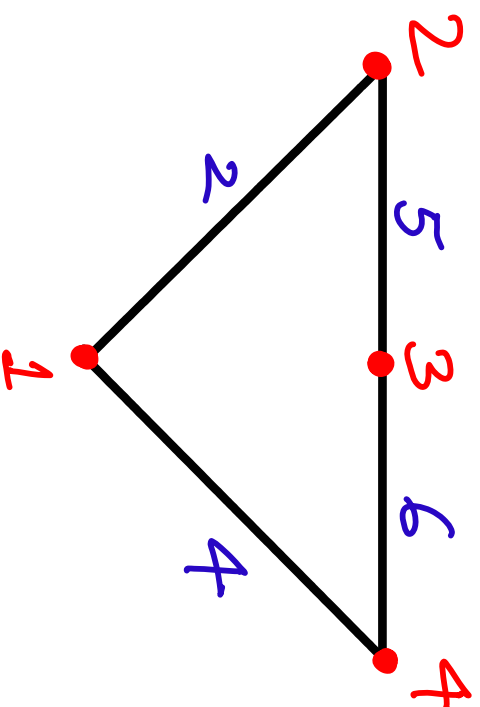
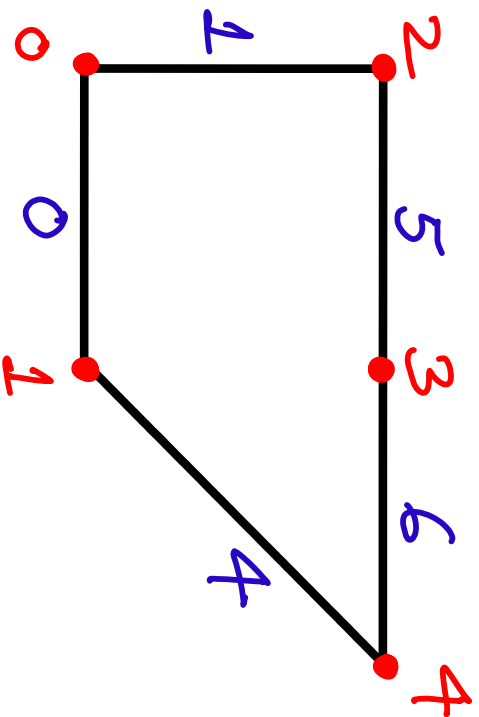


Node in the middle

AN EXAMPLE

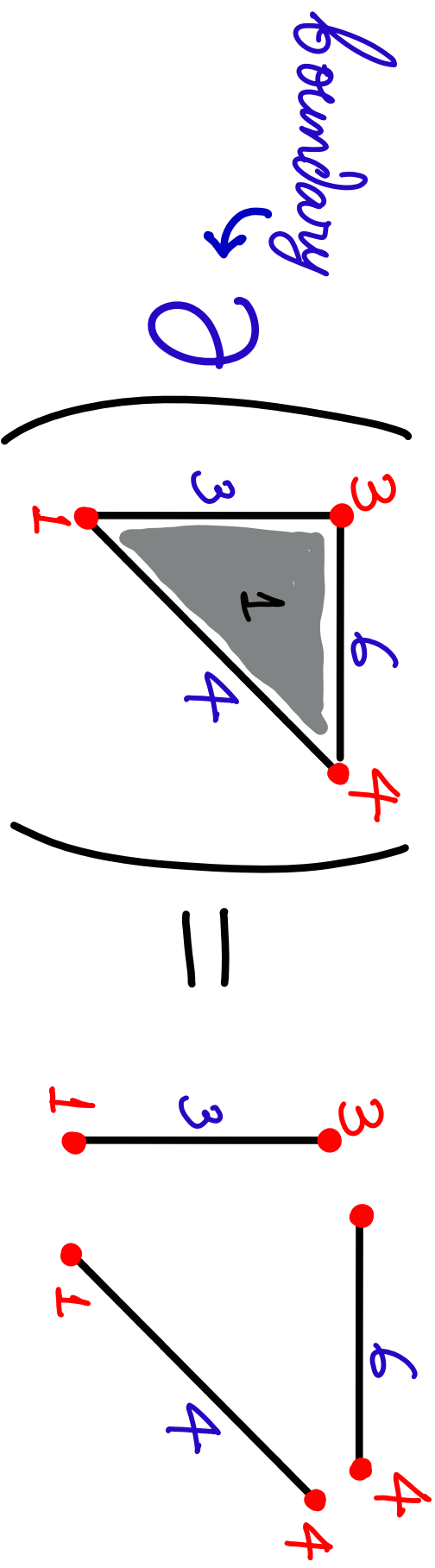


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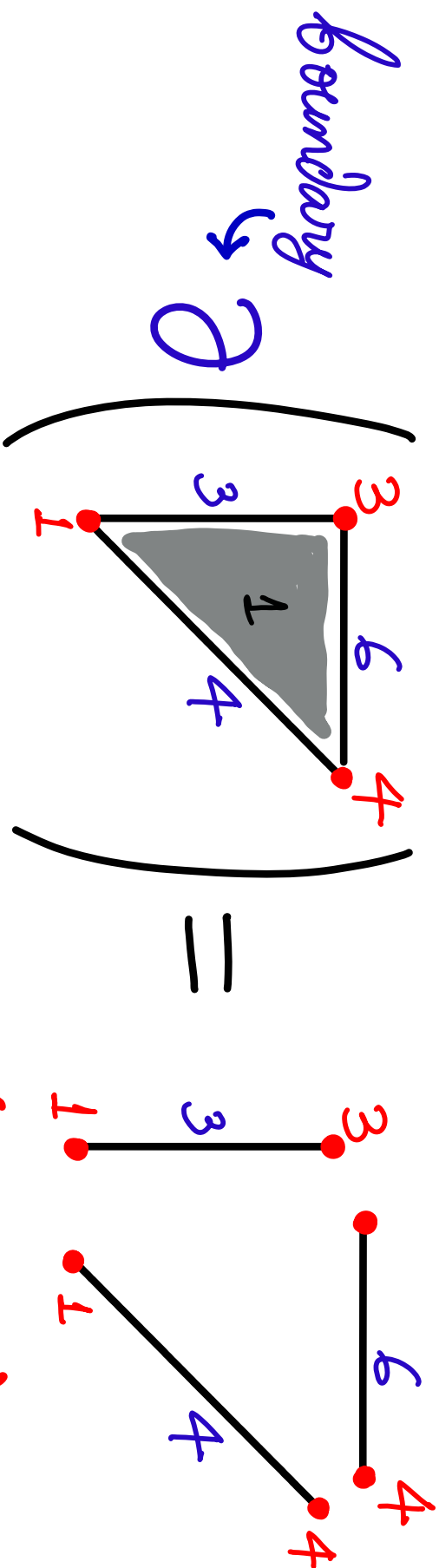


3 cycles representing the same Role

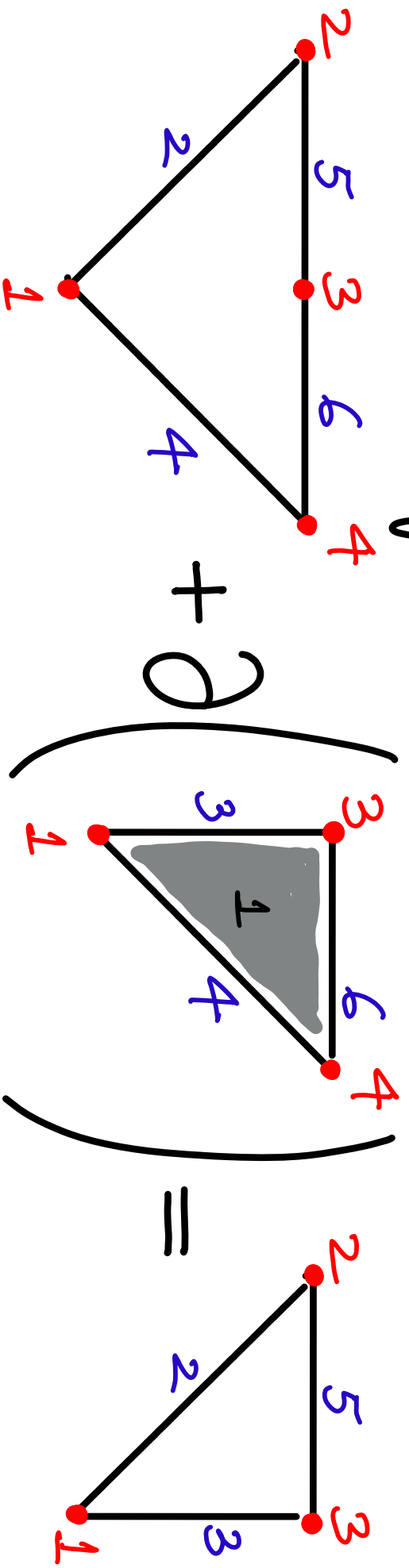
AN EXAMPLE



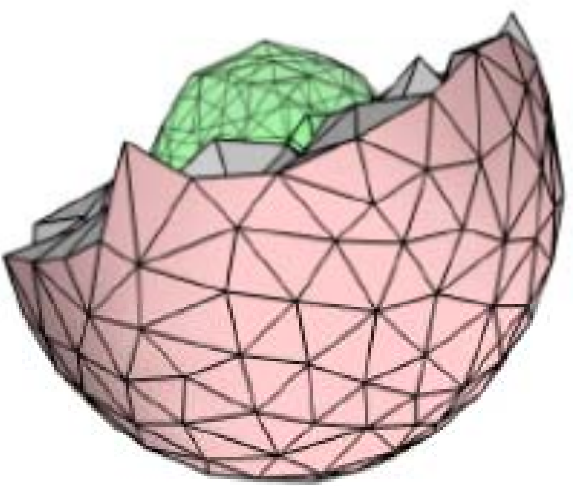
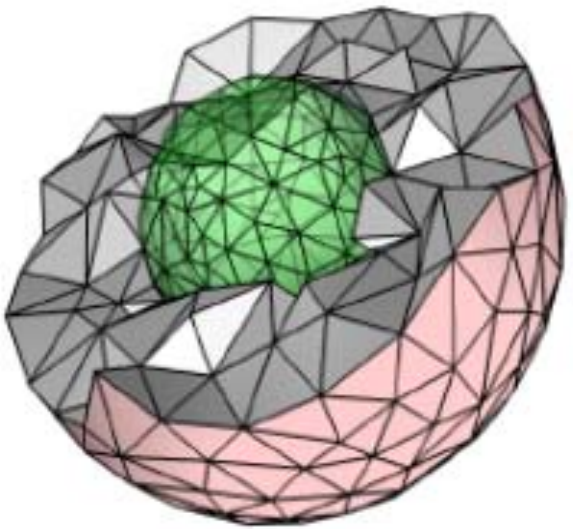
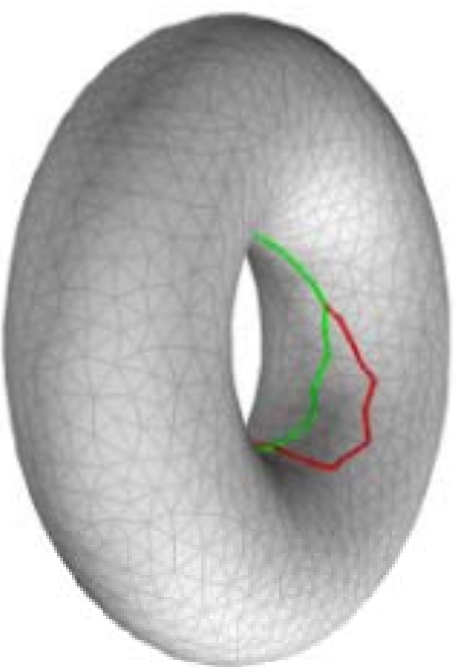
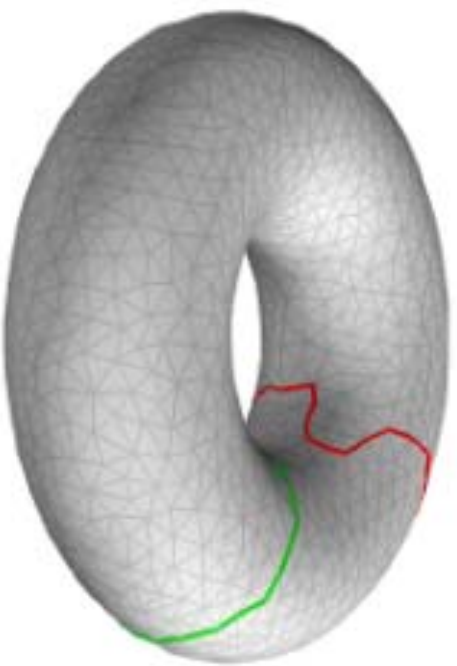
AN EXAMPLE



add edges in \mathbb{Z}_2 ($1+1=0$)

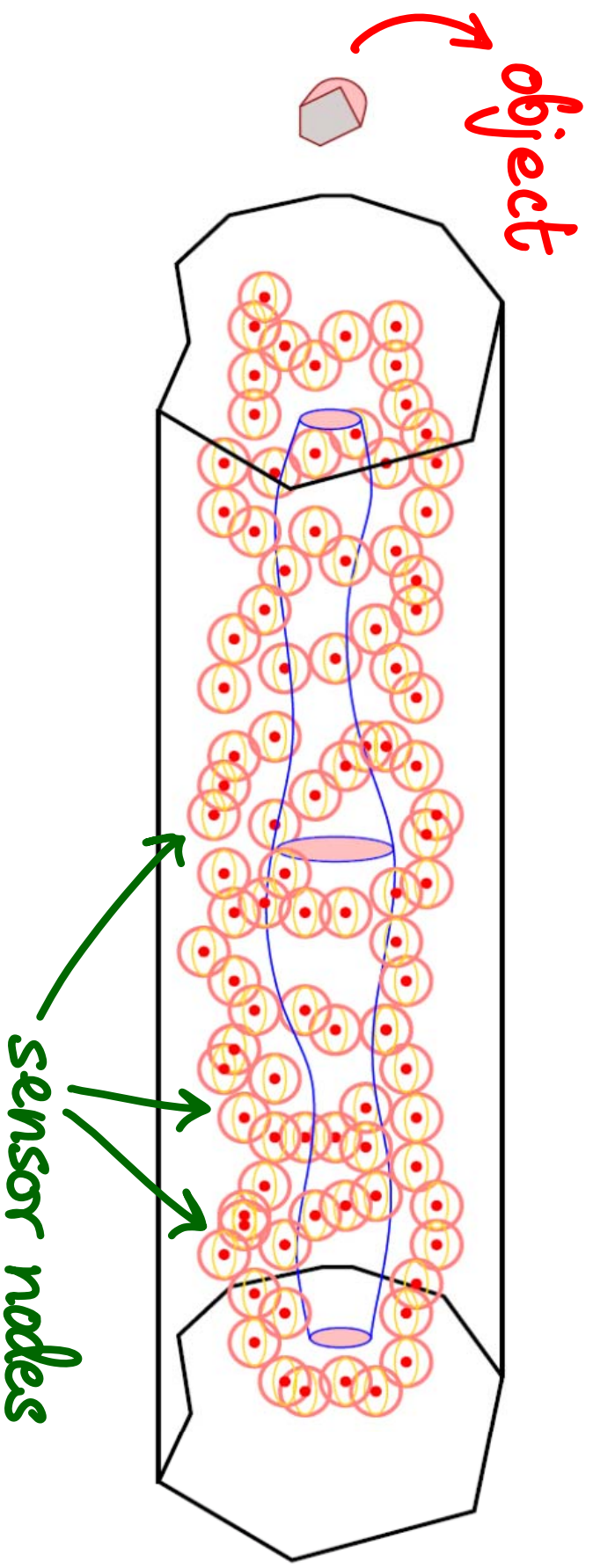


EXAMPLES IN 3D



APPLICATIONS

Sensor networks: object-specific coverage in 3D



Coverage guaranteed if "narrowest neck" in tunnel is smaller than object

APPLICATIONS

tunnels in proteins —
access to active site



(image: CAVER)

Substrate can react with protein
if the "narrowest neck" of tunnel
is "big enough"

RESULTS

X Problem is NP-hard with addition
over \mathbb{Z}_2

RESULTS

- ✗ Problem is NP-hard with addition over \mathbb{Z}_2
- ✓ Addition over \mathbb{Z} : polynomial-time solvable for a large majority of K using linear programming.

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- ✓ topological characterization of total unimodularity (TU)

RESULTS

- ✗ Problem is NP-hard with addition over \mathbb{Z}_2
 - ✓ Addition over \mathbb{Z} : polynomial-time solvable for a large majority of K using linear programming.
 - ✓ topological characterization of total unimodularity (TU)
- Tamal Dey (ohio st.)
Anil Hirani (U. Illinois)
STOC '10
SICOMP '11

RESULTS

✗ Problem is NP-hard with addition over \mathbb{Z}_2

✓ Addition over \mathbb{Z} : Polynomial-time solvable for a large majority of K using linear programming.

✓ topological characterization of total unimodularity (TU)

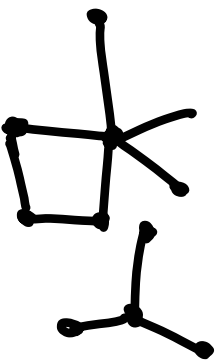
✓ flat norm of currents in simplicial complexes

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Kevin Vixie,
Sharif Ibrahim
(MSU)

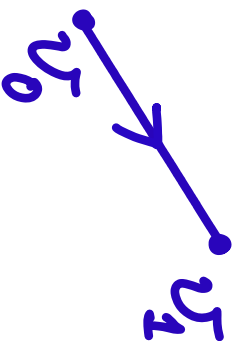
CHAINS

1-chain:

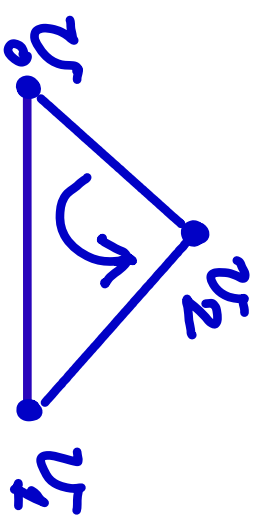


collection of edges

Orientation of a simplex:



$[v_0 v_1]$ or $[v_1 v_0]$



$[v_0 v_1 v_2]$ or $[v_0 v_2 v_1]$

β -Chain c : Function from oriented simplices to \mathbb{Z} :

$c(\sigma) = -c(\sigma')$ if σ and σ' are opposite orientations of same simplex

CHAIN GROUPS

Add p -chains by adding their values over $\mathbb{Z} \Rightarrow$

$C_p(K)$: group of (oriented) p -chains.

Elementary chain of $\sigma \in K$:

$$c(\sigma) = 1,$$

$c(\sigma^{-1}) = -1$, if σ^{-1} : opposite orientation of σ

$$c(\tau) = 0 \quad \forall \tau \neq \sigma, \sigma^{-1}.$$

Result: $C_p(K)$ is free abelian; the elementary chains form a basis for $C_p(K)$.

BOUNDARY OPERATOR

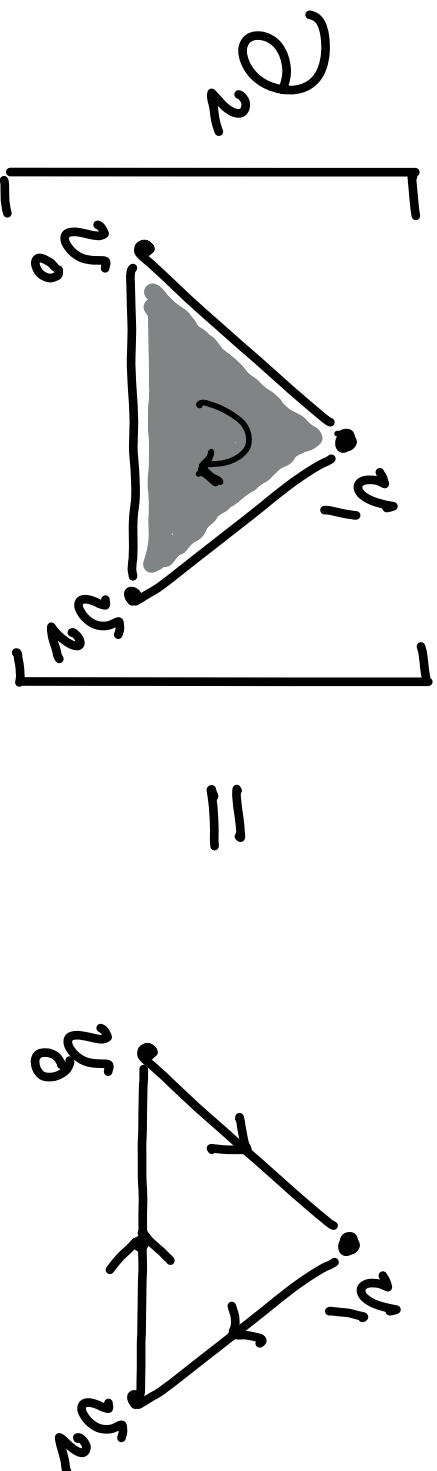
The homomorphism $\partial_p : C_p(K) \rightarrow C_{p-1}(K)$.

$\sigma = [v_0, \dots, v_p]$: oriented simplex, $p > 0$.

$$\partial_p \sigma = \partial_p [v_0, \dots, v_p] = \sum_{i=0}^{p-1} (-1)^i [v_0, \dots, \hat{v}_i, \dots, v_p]$$

delete v_i

e.g., $\partial_2 [v_0, v_1, v_2] = [v_1, v_2] - [v_0, v_2] + [v_0, v_1]$



HOMOLOGY GROUPS

Lemma:

$\partial_{p-1} \circ \partial_p = 0$ boundary of boundary is empty

$\text{Ker } \partial_p = Z_p(K)$ group of p -cycles

$\text{im } \partial_{p+1} = B_p(K)$ group of p -boundaries

$$B_p(K) \subset Z_p(K) \subset C_p(K)$$

$$H_p(K) = Z_p(K) / B_p(K)$$

group of p -cycles that are NOT p -boundaries

p^{th} homology group of K .

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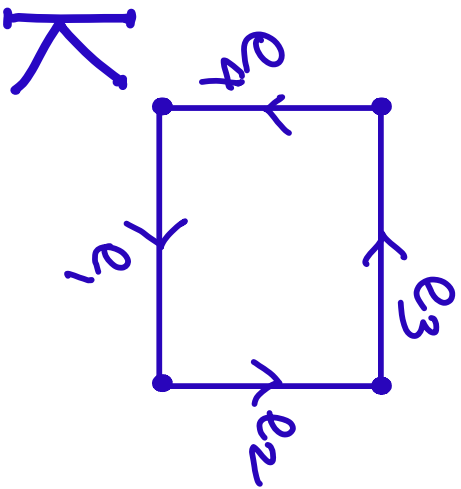
could study $H_p(K, G)$ for $G = \mathbb{Z}, \mathbb{Z}_2, \mathbb{Q}$, etc.

$$H_p(K) = Z_p(K) / B_p(K)$$

\mathbb{Z}_2 : widely used for computation.
field, simple, intuitive

group of p -cycles that are NOT p -boundaries
 p^{th} homology group of K .

EXAMPLE



$C_1(K)$: free abelian of rank 4
general 1-chain: $C = \sum_{i=1}^4 n_i e_i$
 C is a cycle $\Leftrightarrow n_1 = n_2 = n_3 = n_4$

$\Rightarrow Z_1(K)$ is infinite cyclic, generated by
 $e_1 + e_2 + e_3 + e_4$

No 2-simplices in $K \Rightarrow B_1(K)$ is trivial.

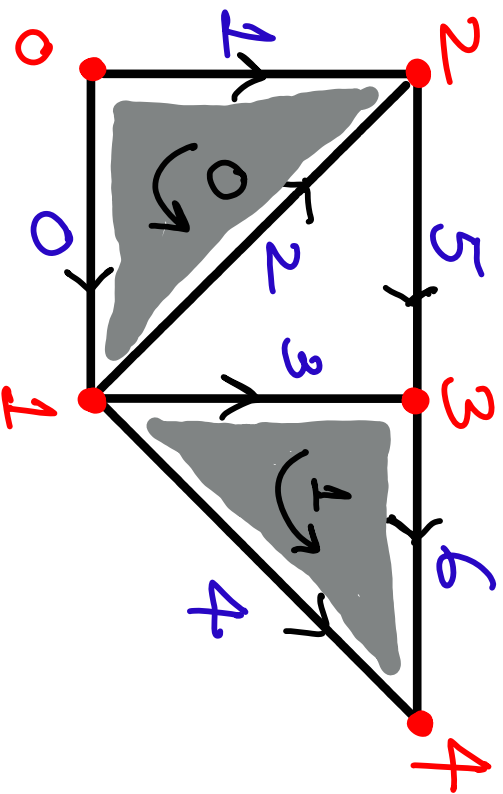
$\Rightarrow H_1(K) = Z_1(K) / B_1(K) \cong \mathbb{Z}$.

BOUNDARY MATRIX $[a_p]$

$$\partial_p: C_p(K) \rightarrow C_{p-1}(K)$$

if $\{\sigma_i\}_{i=0}^{m-1}$ and $\{\tau_j\}_{j=0}^{n-1}$ are elementary chain bases for $C_{p-1}(K)$ & $C_p(K)$, then

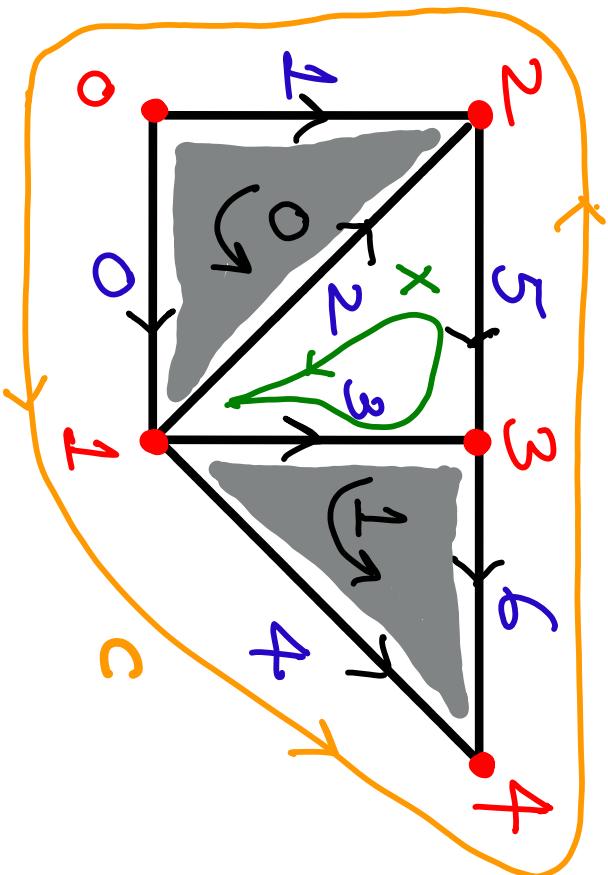
$[a_p]$ is an $m \times n$ matrix, $[a_p]_{ij} \in \{-1, 0, 1\}$.



$$[a_2] =$$

$$\begin{matrix} & 0 & 1 \\ \begin{matrix} 0 \\ 1 \\ 2 \\ 3 \\ 4 \\ 5 \\ 6 \end{matrix} & \begin{bmatrix} 1 & 0 \\ -1 & 0 \\ 1 & 0 \\ 0 & 0 \\ 0 & 0 \\ 0 & 0 \\ -1 & 0 \end{bmatrix} \end{matrix}$$

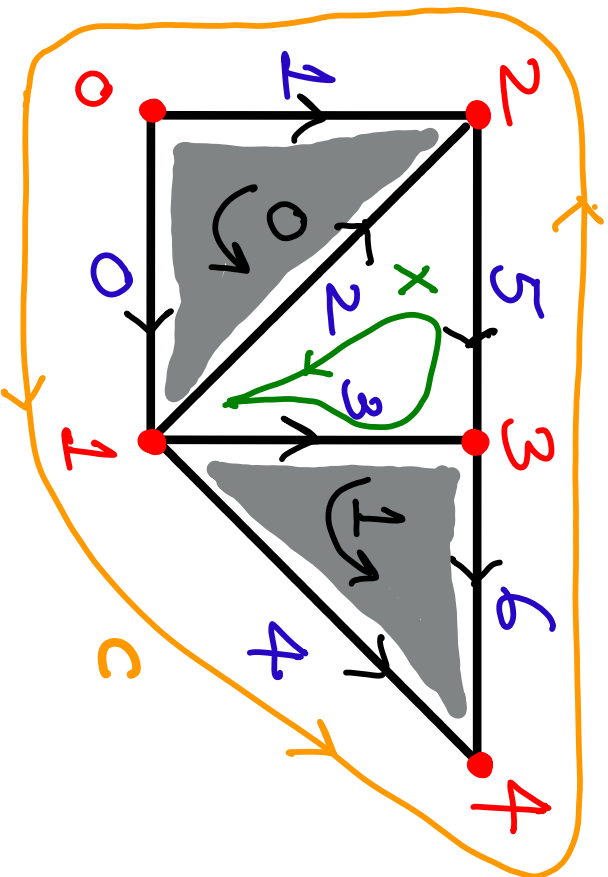
SHORT HOMOLOGOUS CYCLES



$$c = \begin{bmatrix} -1 \\ 0 \\ 1 \\ -1 \\ -1 \end{bmatrix}$$

represents hole in middle, but has 5 edges.

SHORT HOMOLOGOUS CYCLES



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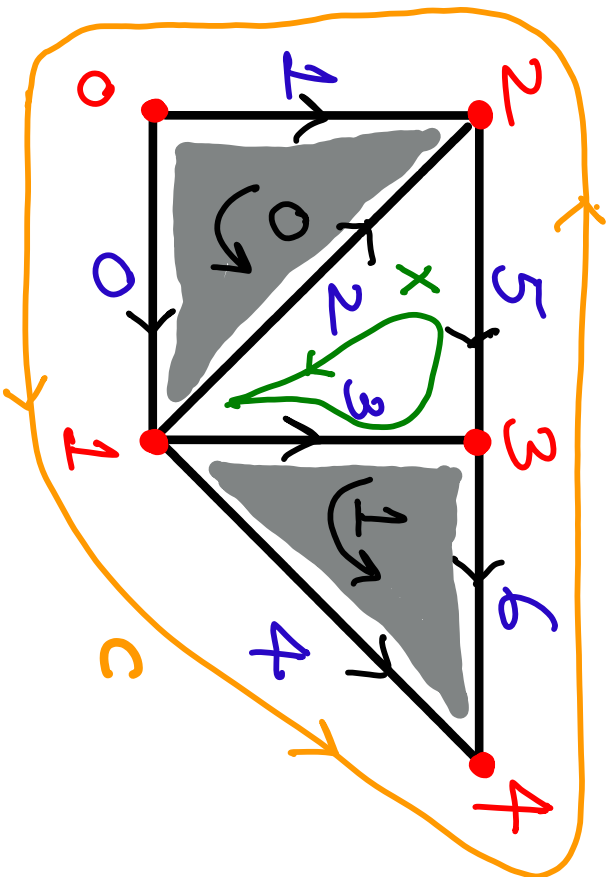
represents hole in middle, but has 5 edges.

$$x = \begin{bmatrix} 0 \\ 0 \\ -1 \\ 1 \\ 0 \\ -1 \\ 0 \end{bmatrix}$$

is homologous to c , but is shorter (has only 3 edges)

x is "tightest" cycle around the hole

SHORT HOMOLOGOUS CYCLES



$$[\partial_2] = \begin{matrix} & 0 & 1 \\ \begin{matrix} 0 \\ 1 \\ 2 \\ 3 \\ 4 \\ 5 \\ 6 \end{matrix} & \begin{bmatrix} 1 & 0 \\ -1 & 0 \\ 1 & 0 \\ 0 & -1 \\ 0 & 1 \\ 0 & 0 \\ 0 & -1 \end{bmatrix} \end{matrix}$$

$$x = c + [\partial_2][^{-1}]$$

$x \sim c$ (x is homologous to c)

$$c = \begin{bmatrix} -1 \\ 0 \\ 1 \\ -1 \end{bmatrix}$$

$$x = \begin{bmatrix} 0 \\ -1 \\ 1 \\ 0 \end{bmatrix}$$

Can study weighted (in \mathbb{R})
chains/cycles (instead of

± 1 weights)

OPTIMAL HOMOLOGOUS CYCLE PROBLEM

OHCSP: Given a p -cycle c in K , find a cycle c^* with smallest value of $\|wc^*\|_1$
Among all cycles homologous to c .

$W = \text{diag}(w_1, \dots, w_m)$, where $w_i \in \mathbb{R}_{\geq 0}$ is the weight of p -simplex $\sigma_i \in K$.

OPTIMAL HOMOLOGOUS CYCLE PROBLEM

DHCP: Given a p -cycle c in K , find a cycle c^* with smallest value of $\|wc^*\|_1$
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With homology defined over \mathbb{Z}_2 , DHCP is NP-hard (Chen & Freedman, 2010)

OPTIMAL HOMOLOGOUS CHAIN PROBLEM

DHCP: Given a p -chain c in K , find a chain c^* with smallest value of $\|wc^*\|_1$ among all chains homologous to c .

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OHCIP AS AN INTEGER PROGRAM

$\min_{x,y} \|Wx\|_1$ such that

$$x = c + [a_{p+1}]y, \quad x \in \mathbb{Z}^m, \quad y \in \mathbb{Z}^n$$

OHCIP AS AN INTEGER PROGRAM

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$\sum_i |w_i| |x_i|$ \rightarrow *piecewise linear*

OHCIP AS AN INTEGER PROGRAM

$\min_{x,y} \|Wx\|_1$ such that $= \sum_i |w_i| |x_i|$
piecewise linear

$$x = c + [a_{p+1}]y, \quad x \in \mathbb{Z}^m, \quad y \in \mathbb{Z}^n$$

$$\min \sum_i |w_i| (x_i^+ + x_i^-) \quad (\text{IP})$$

$$\text{s.t. } x^+ - x^- = c + [a_{p+1}]y$$

$$x^+, x^- \geq 0, \quad x^+, x^- \in \mathbb{Z}^m, \quad y \in \mathbb{Z}^n$$

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ignore to get LP relaxation

IP AND TOTAL UNIMODULARITY

$$\min \{c^T x \mid Ax = b, x \geq 0, x \in \mathbb{Z}^n\} \text{ (IP)} \quad \left\{ \begin{array}{l} A \in \mathbb{Z}^{m \times n} \\ b \in \mathbb{Z}^m \end{array} \right.$$

$$\min \{c^T x \mid Ax = b, x \geq 0\} \text{ (LP)}$$

IP AND TOTAL UNIMODULARITY

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Result: (IP) can always be solved in polynomial time by solving (LP) iff A is totally unimodular.

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A is TU if every square submatrix has determinant $-1, 0$, or 1 .

In particular, $A_{ij} \in \{-1, 0, 1\} \forall i, j$.

IP AND TOTAL UNIMODULARITY

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e.g., node-arc incidence matrix of graph

OHCIP AND TU OF $[\partial_{p_{H1}}]$

$$\min \sum_i |w_i| (x_i^+ + x_i^-)$$

$$\text{s.t. } x^+ - x^- = c + [\partial_{p_{H1}}] \gamma \quad (\text{LP})$$

$$x^+, x^- \geq 0$$

The constraint matrix of above LP is TU iff $[\partial_{p_{H1}}]$ is TU.

OHCP AND TU OF $[a_{p+1}]$

$$\min \sum_i |w_i| (x_i^+ + x_i^-)$$

$$\text{s.t. } x^+ - x^- = c + [a_{p+1}] \gamma \quad (\text{LP})$$

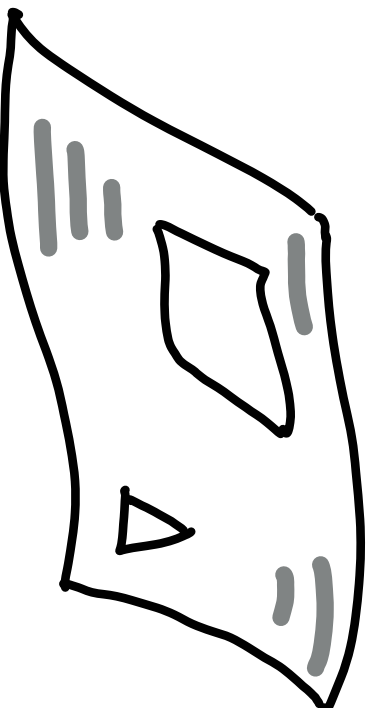
$$x^+, x^- \geq 0$$

The constraint matrix of above LP is TU iff $[a_{p+1}]$ is TU.

\Rightarrow OHCP (with homology defined over \mathbb{Z}) is solvable in polynomial time iff $[a_{p+1}]$ is TU.

ORIENTABLE MANIFOLDS

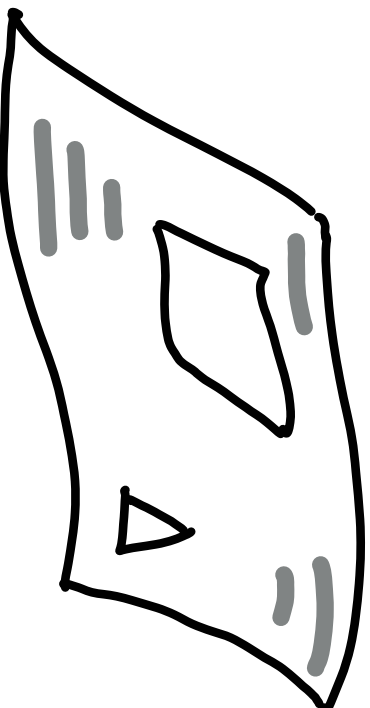
Consistent orientation of $(p+1)$ -manifold M : Orient $(p+1)$ -simplices s.t. $(p+1)$ -boundary is carried by ∂M .



possibly empty

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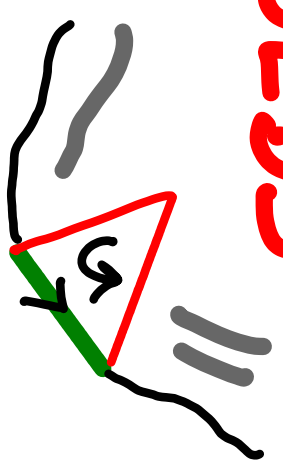
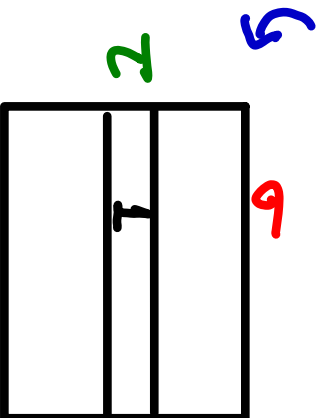


possibly empty

Theorem 1. For a finite simplicial complex triangulating a compact orientable manifold, $[\partial_{p+1}]$ is TU.

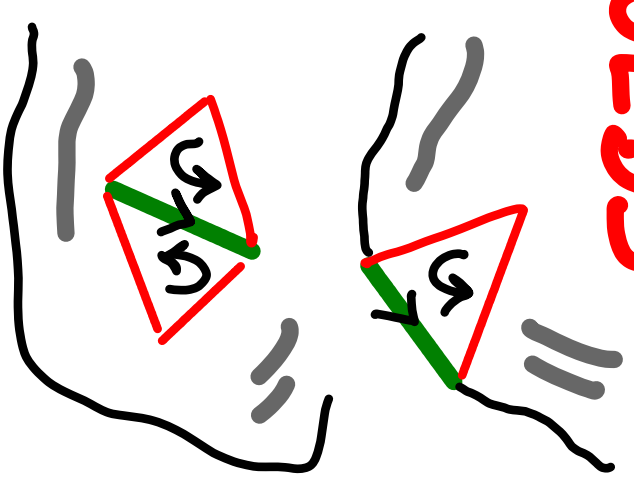
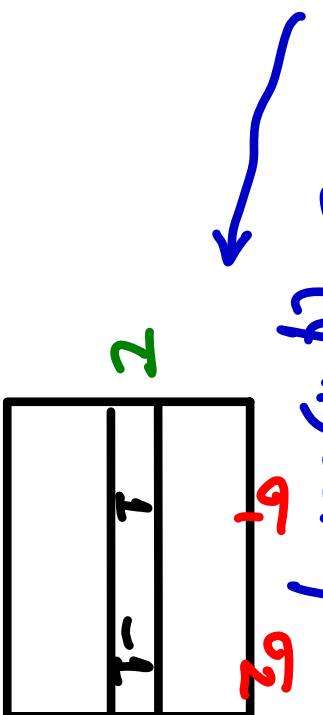
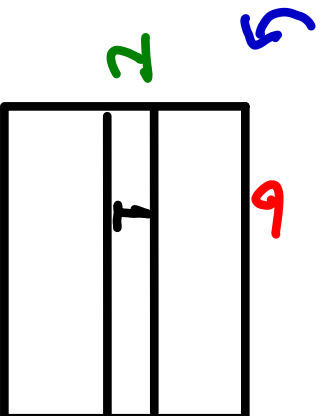
ORIENTABLE MANIFOLDS

Proof: τ (p -simplex): face of $(p+1)$ -simplices



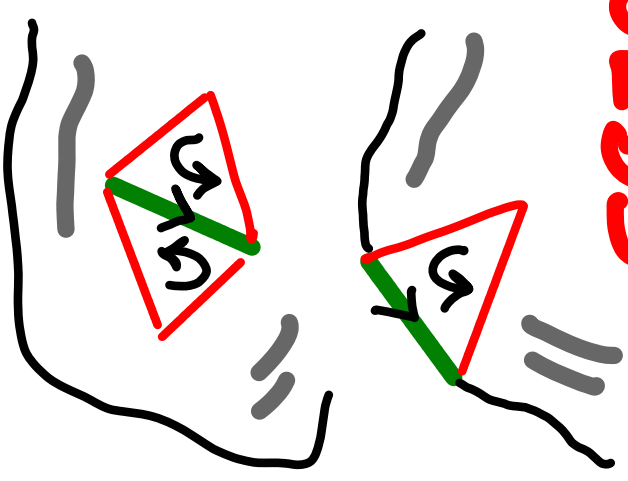
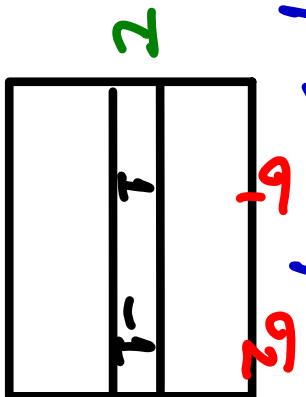
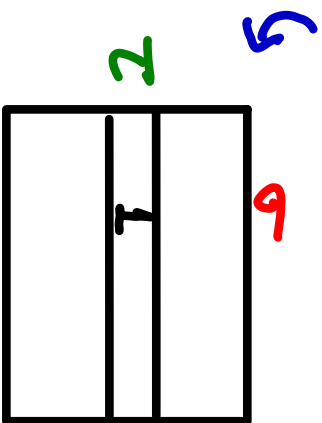
ORIENTABLE MANIFOLDS

Proof: τ (p -simplex): face of one or two σ 's ($(p+1)$ -simplices)



ORIENTABLE MANIFOLDS

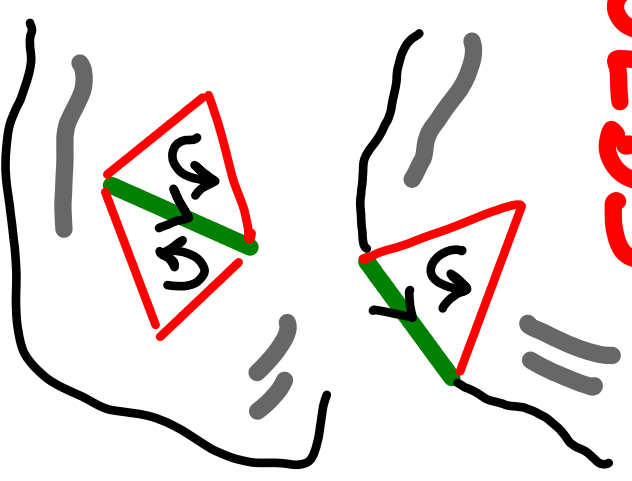
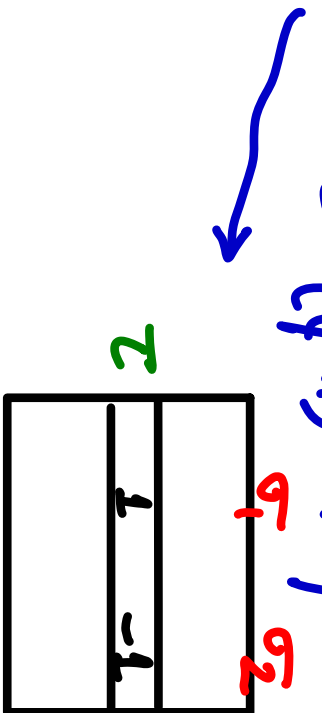
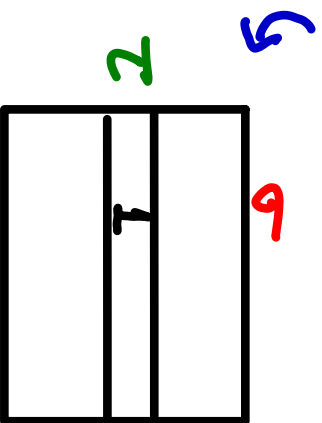
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$\Rightarrow [a_{p+1}]^T$ satisfies sufficient condition for TU.
 (Heller & Tompkins, 1956) $\Rightarrow [a_{p+1}]$ is TU.

ORIENTABLE MANIFOLDS

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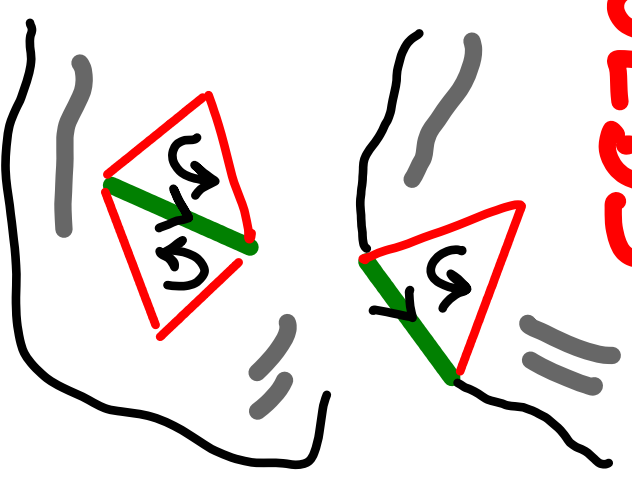
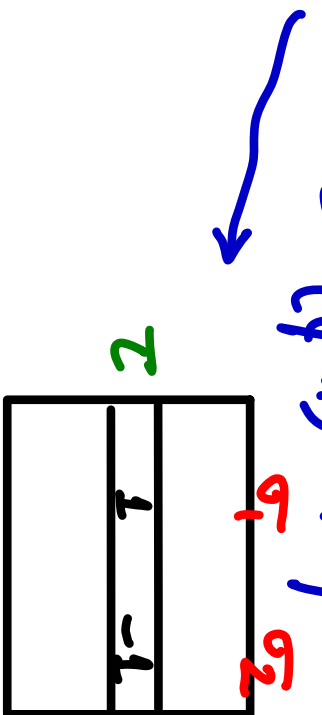
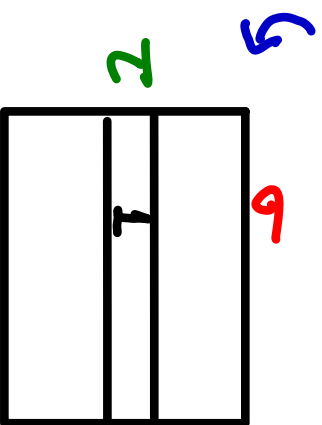


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 (Heller & Tompkins, 1956) $\Rightarrow [a_{p+1}]$ is TU.

Arbitrary orientations \equiv Scale rows/columns of $[a_{p+1}]$ by $-1 \Rightarrow$ preserves TU.

ORIENTABLE MANIFOLDS

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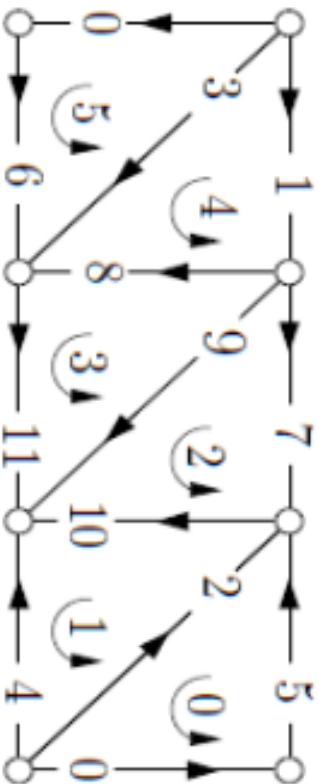
$\Rightarrow [a_{p+1}]^T$ satisfies sufficient condition for TU.
 (Heller & Tompkins, 1956) $\Rightarrow [a_{p+1}]$ is TU.

Arbitrary orientations \equiv scale rows/columns of $[a_{p+1}]$ by $-1 \Rightarrow$ preserves TU.

Also observed by John Sullivan (1992)

NON-ORIENTABLE MANIFOLDS

Möbius strip:

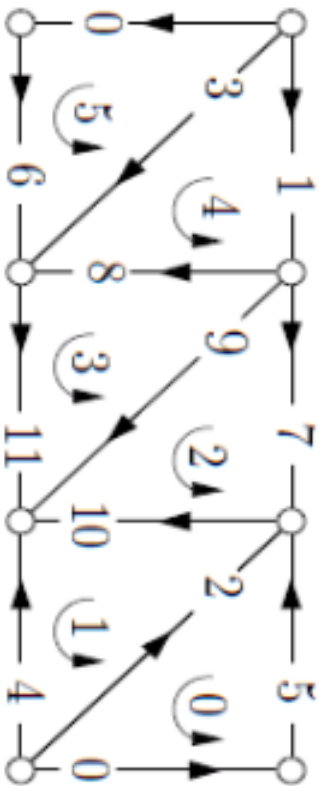


$[B_2]$ for Möbius strip:

	0:	1:	2:	3:	4:	5:
0:	1	0	0	0	0	1
1:	0	0	0	0	-1	0
2:	-1	1	0	0	0	0
3:	0	0	0	0	1	-1
4:	0	-1	0	0	0	0
5:	1	0	0	0	0	0
6:	0	0	0	0	0	1
7:	0	0	-1	0	0	0
8:	0	0	0	1	-1	0
9:	0	0	1	-1	0	0
10:	0	1	-1	0	0	0
11:	0	0	0	1	0	0

NON-ORIENTABLE MANIFOLDS

Möbius strip:



$[\partial_2]$ for Möbius strip:

	0:	1:	2:	3:	4:	5:
0:	1	0	0	0	0	1
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$$S = \begin{bmatrix} 5 & 4 & 3 & 2 & 1 & 0 \\ 1 & 0 & 0 & 0 & 0 & 1 \\ -1 & 1 & 0 & 0 & 0 & 0 \\ 0 & -1 & 1 & 0 & 0 & 0 \\ 0 & 0 & -1 & 1 & 0 & 0 \\ 0 & 0 & 0 & -1 & 1 & 0 \\ 0 & 0 & 0 & 0 & 1 & -1 \end{bmatrix}$$

$\begin{matrix} 0 \\ 3 \\ 8 \\ 9 \\ 10 \\ 2 \end{matrix}$

$\det S = -2. \Rightarrow [\partial_2]$ is not TU.

MAIN RESULT

Theorem 2: $[a_{pH}]$ is TU iff $H_p(L, L_0)$ is torsion-free for all pure subcomplexes L, L_0 of K of dimensions (pH) and p , respectively, where $L_0 \subset L$.

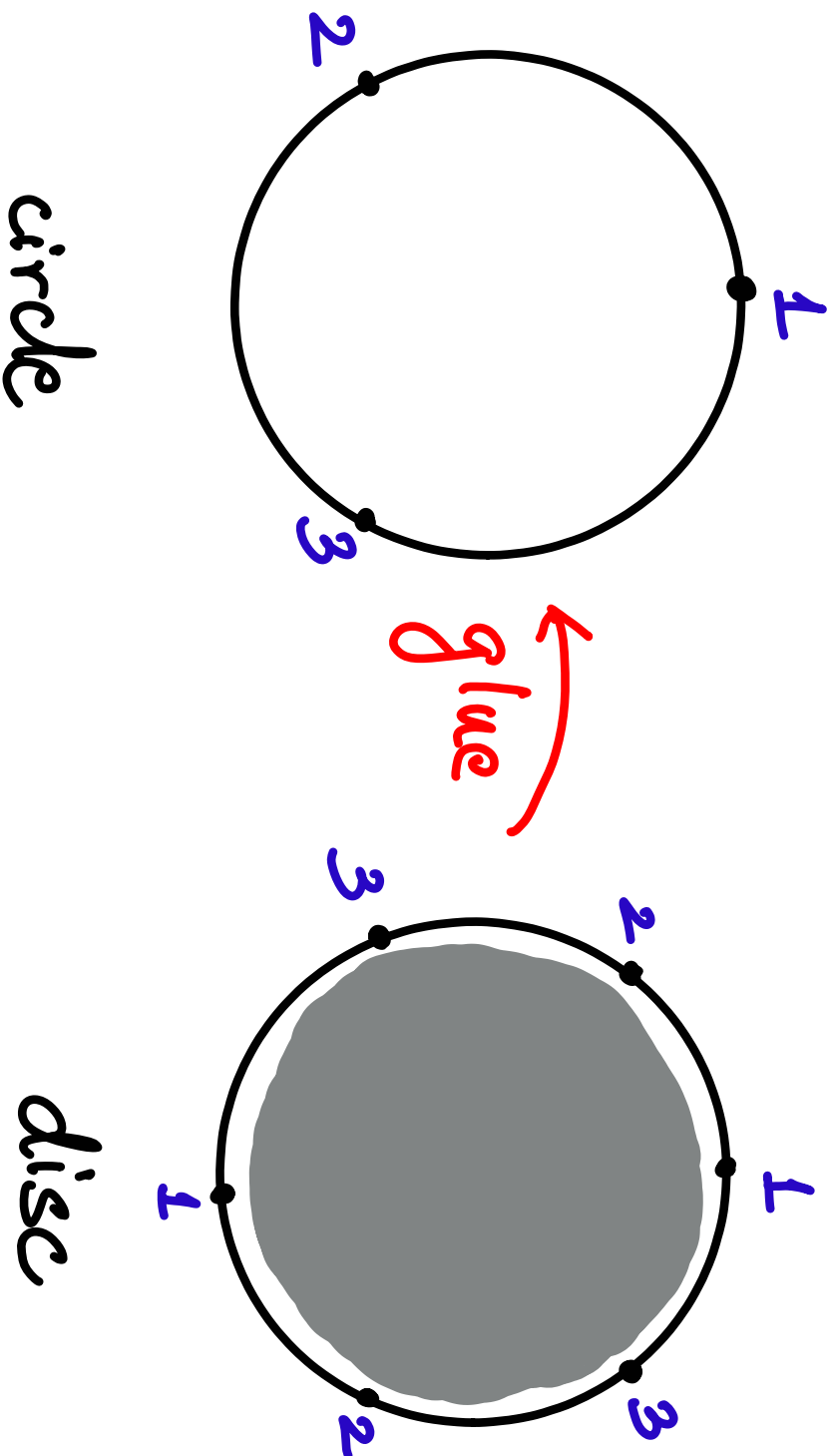
MAIN RESULT

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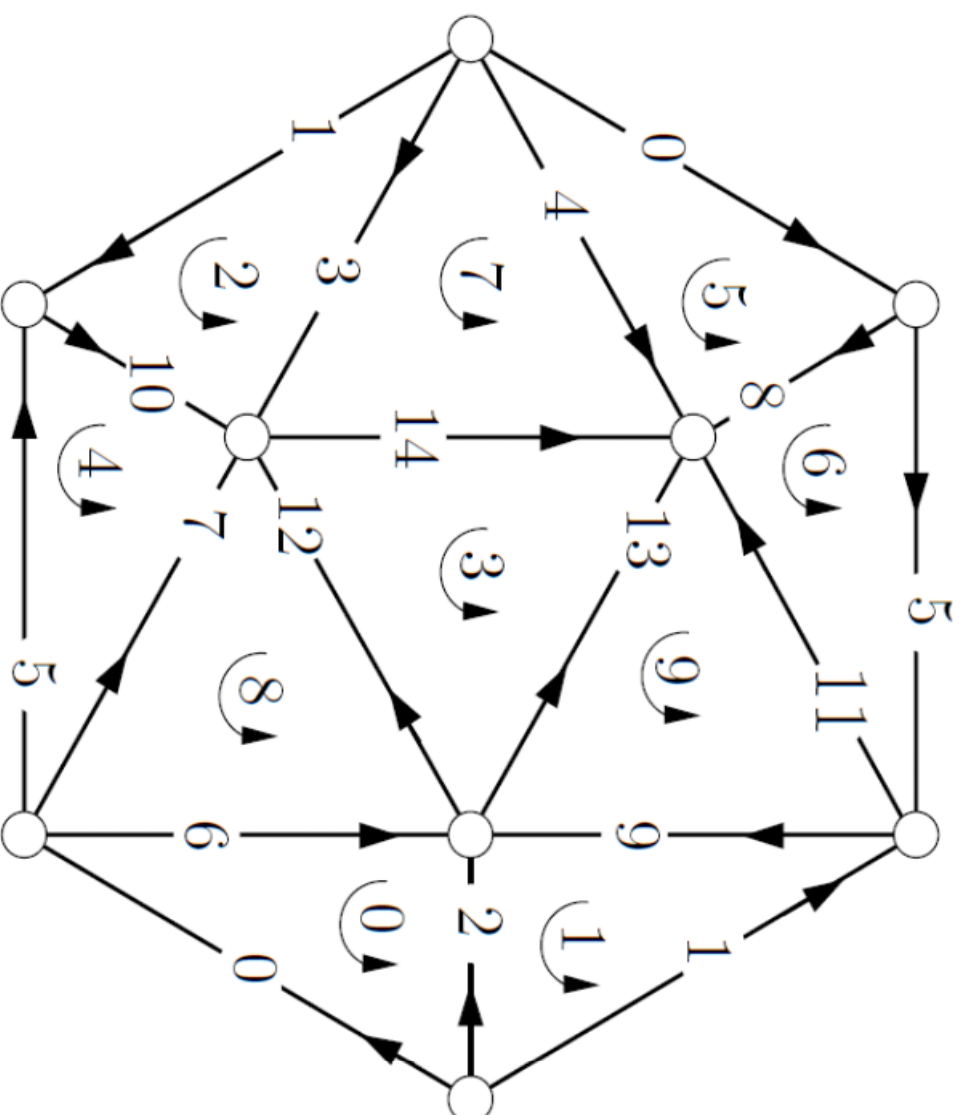
* topological characterization of TU.

VISUALIZE TORSION

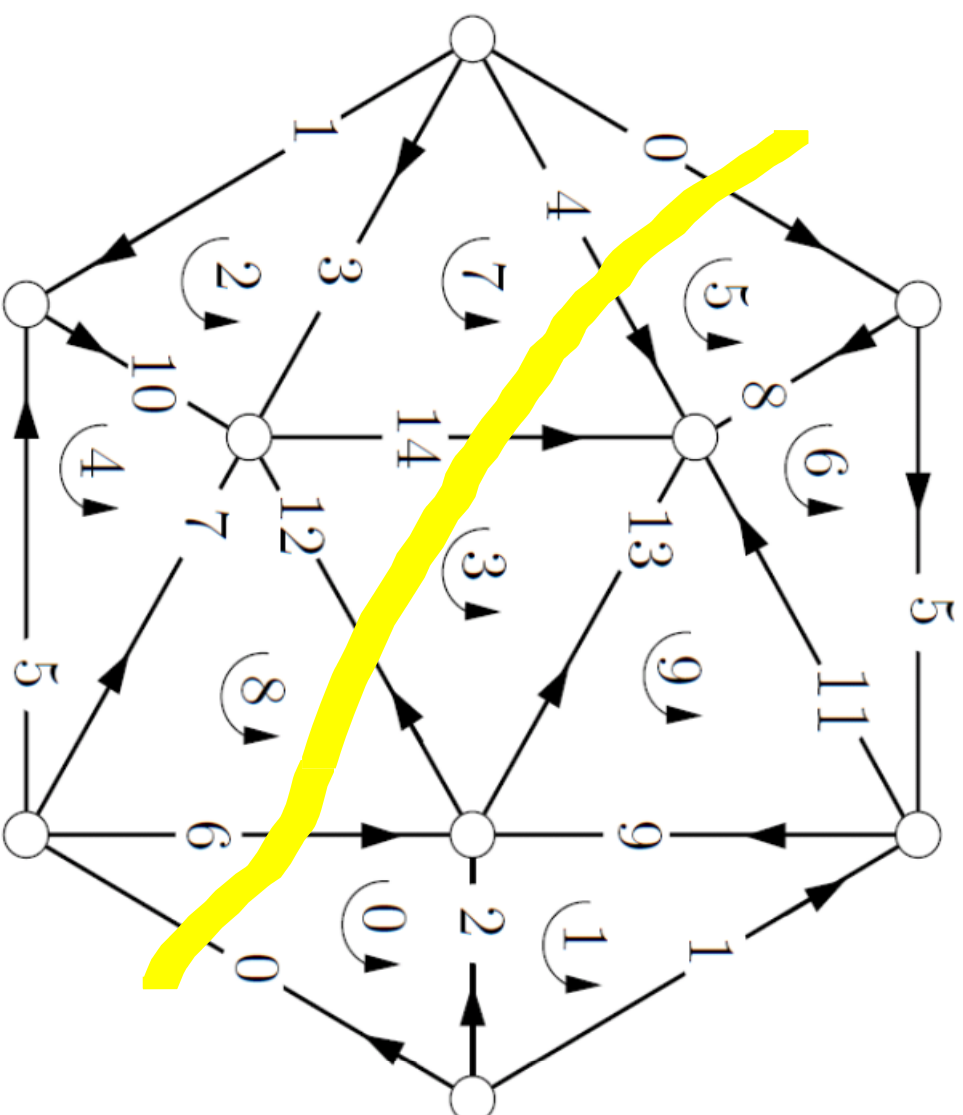


Poincaré (1899): Projective Plane
(or Dunce hat)

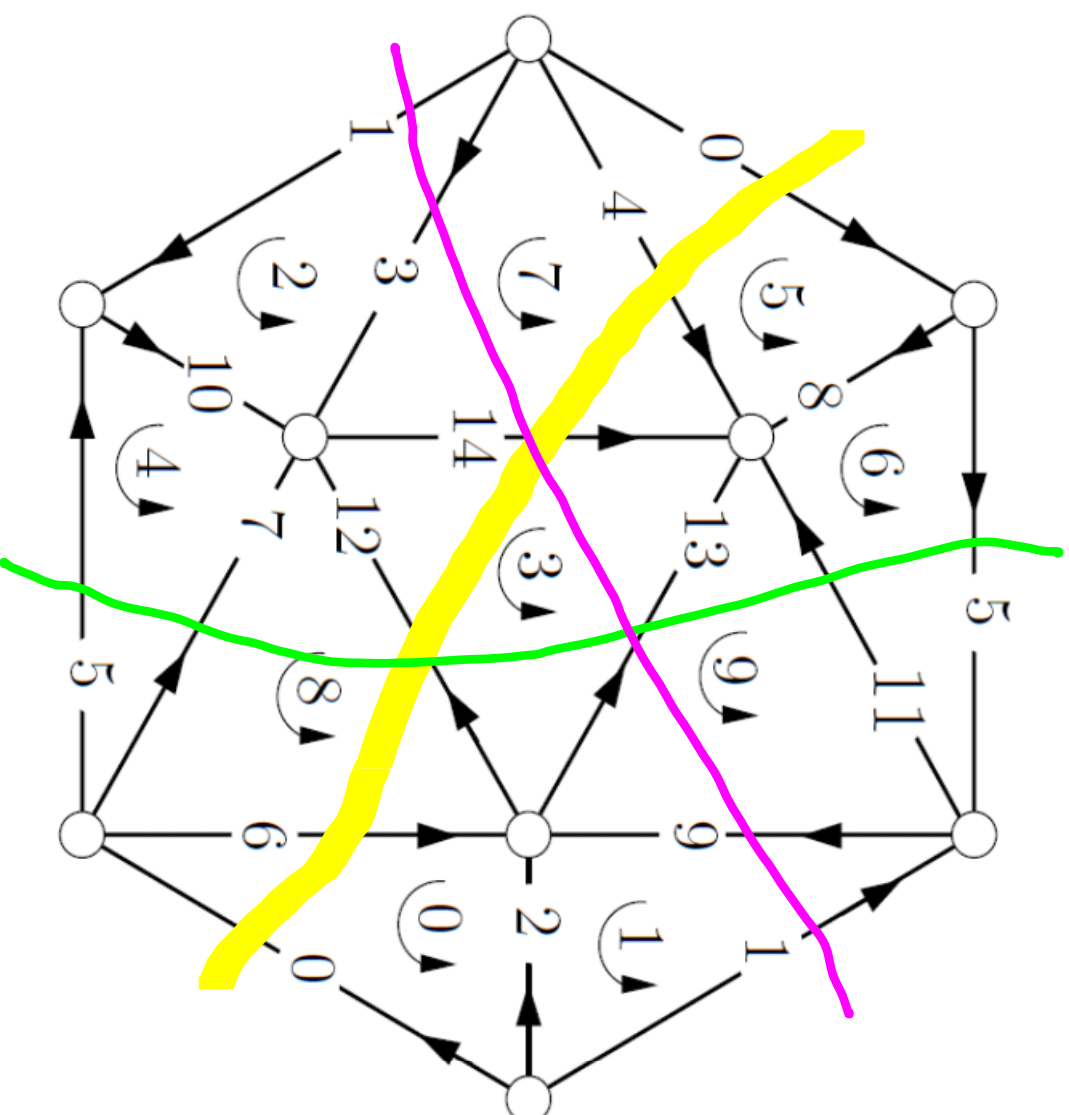
PROJECTIVE PLANE



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→ $[D_p]$ is TU $\iff K$ is orientable manifold

→ $[D_d]$ is TU $\iff K$ embedded in \mathbb{R}^d

e.g., tetrahedra - triangles $[D_3]$ in \mathbb{R}^3

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- collections of oriented sets with integer multiplicities

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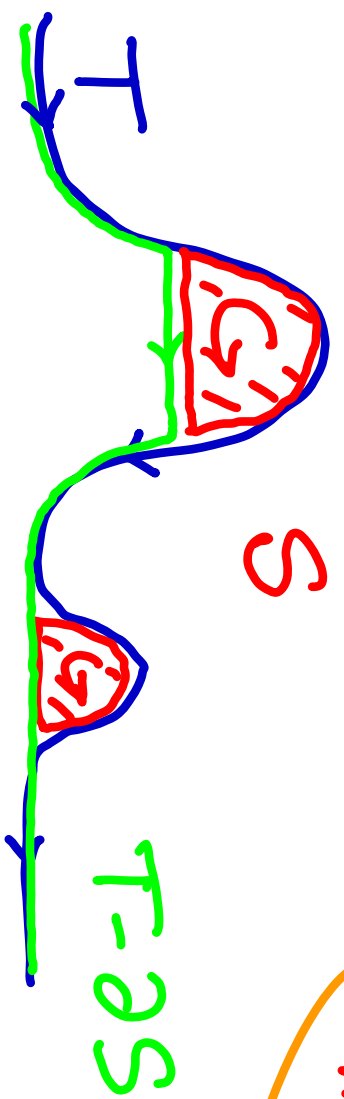
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$$\text{s.t. } x = t - [\partial_{d+1}] s \quad |x_i|, |s_j| \rightarrow \text{linearize}$$
$$x \in \mathbb{Z}^m, s \in \mathbb{Z}^n \quad w_i, v_j: \text{volumes}$$

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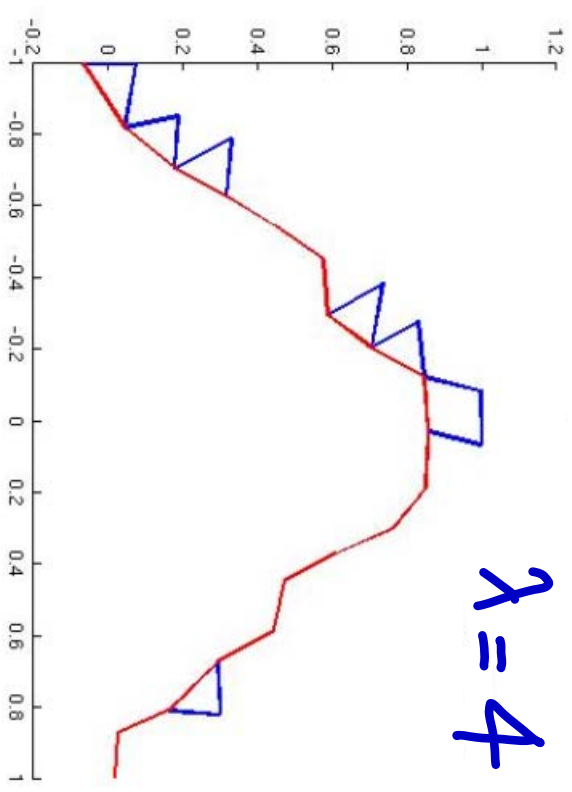
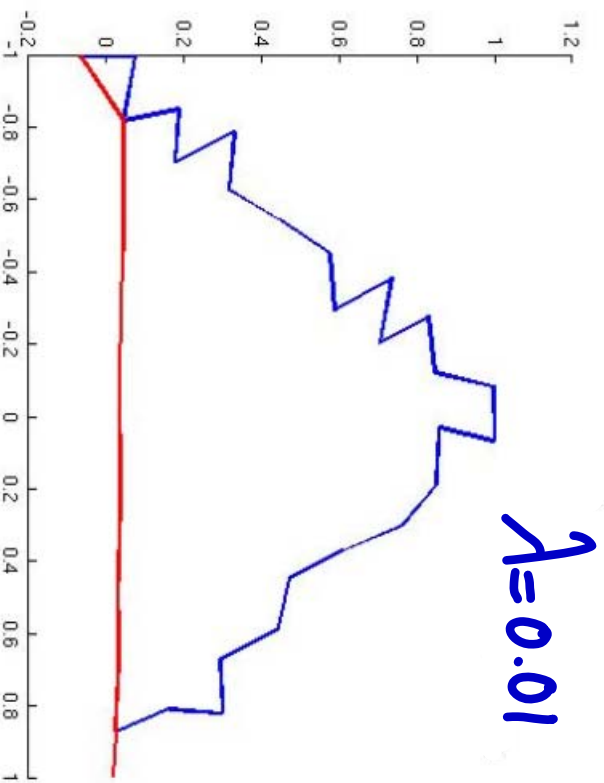
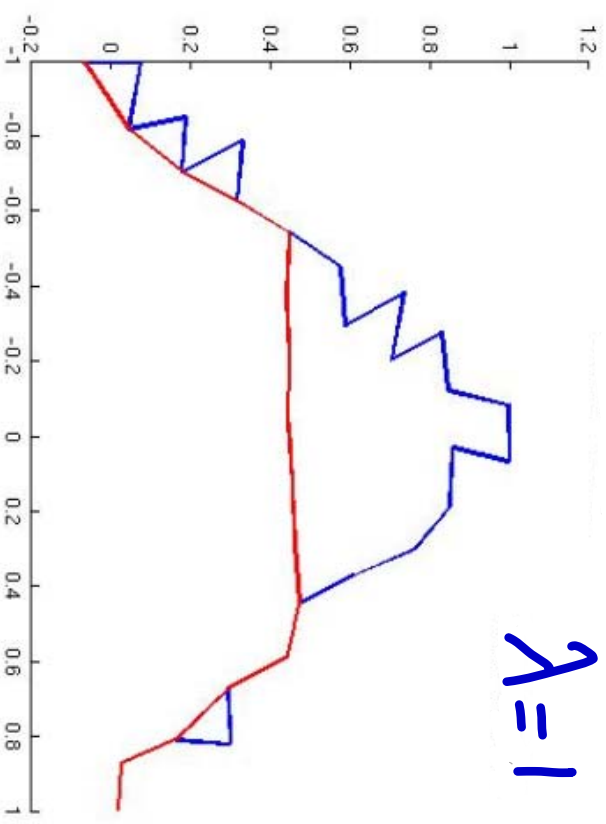
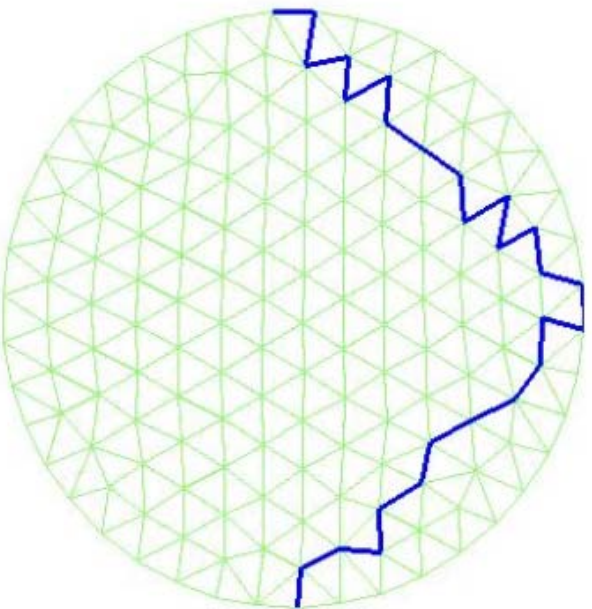
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Similar to OHTCP LP

- Simplicial deformation theorem: can push any current onto simplicial complex in a controlled manner

ILLUSTRATION



OPEN QUESTIONS

- * Can we still get integral solution in the presence of relative torsion?
- * Faster algos to solve OHC P/MSFN LPs?
- * LP for optimal homology basis?
- * Shape signatures from flat norm with scale?